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## Opinion

## Temporal Coding of Visual Space

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Establishing a representation of space is a major goal of sensory systems. Spatial information, however, is not always explicit in the incoming sensory signals. In most modalities it needs to be actively extracted from cues embedded in the temporal flow of receptor activation. Vision, on the other hand, starts with a sophisticated optical imaging system that explicitly preserves spatial information on the retina. This may lead to the assumption that vision is predominantly a spatial process: all that is needed is to transmit the retinal image to the cortex, like uploading a digital photograph, to establish a spatial map of the world. However, this deceptively simple analogy is inconsistent with theoretical models and experiments that study visual processing in the context of normal motor behavior. We argue here that, as with other senses, vision relies heavily on temporal strategies and temporal neural codes to extract and represent spatial information.

## Stable Visual Representations, but a Moving Visual Image

Like a camera, the eye forms an image of the external scene on its posterior surface where the retina is located, with its dense mosaic of **photoreceptor cells** (see [Glossary](#)) that convert light into electrochemical signals. At each moment in time, all spatial information is present in the visual signals striking the photoreceptors, which explicitly encode space by their position within the retinal array. This **camera model of the eye** and the **spatial coding** idea have long dominated visual neuroscience. Although the specific reference frames of spatial representations (e.g., retinotopic vs spatiotopic) have been intensely debated [1,2], spatial information has always been assumed to originate from the receptor layout in the retina.

Alas, the eye does not behave like a camera. While a photographer usually takes great care to ensure that the camera does not move, the eyes insist on moving continuously [3–6]. Humans perform rapid gaze shifts, known as **saccades**, 2–3 times per second. Even though models of the visual system often assume that the visual input is a stationary image during **fixational pauses** between successive saccades, small eye movements, known as **fixational eye movements**, continually occur. These movements displace the stimulus by considerable amounts on the retina, therefore continually changing the light signals striking the photoreceptors [7,8] ([Box 1](#)).

Furthermore, unlike the film in a camera, the visual system depends on temporal transients. Neurons in the retina, thalamus, and later stages of the visual pathways respond strongly to temporal changes [9–13]. Visual percepts tend to fade away in the complete absence of temporal transients [14–17], and spatial changes that occur too slowly are not even detected by humans [18,19].

These considerations do not appear compatible with the standard idea that space is encoded solely by the position of neurons within spatial maps. They suggest that the visual system combines spatial sampling with temporal processing to extract and encode spatial information.

## Highlights

The input to the visual system is not a static image: incessant eye movements continuously reformat input signals, transforming spatial patterns into temporal modulations on the retina.

Luminance modulations resulting from different types of eye movements have different spatiotemporal frequency distributions. Saccade transients enhance lower spatial frequencies than those enhanced by the fixational drift.

Recent experiments that manipulated oculomotor transients indicate that humans are sensitive to these temporal modulations. The natural alternation between saccade and fixational drift sets the stage for a coarse-to-fine analysis of the scene.

Encoding of spatial information in the visual system does not only rely on the position of neurons within maps, but also relies on temporal processing of luminance modulations resulting from eye movements.

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In this article we describe specific mechanisms by which this process may take place, and we briefly review supporting evidence. We specifically focus on the input signals resulting from eye movements because these induce the most common temporal changes experienced by the retina.

### The Need for Spatiotemporal Codes

Most agree that at some level the visual system must integrate spatial information over time. Unlike the uniform resolution of a photograph acquired by a conventional camera, the image projected onto the retina is sampled by the neural array in a highly non-homogeneous manner. Only in a very small region at the center of gaze, the **fovea**, are cones packed sufficiently tightly to allow the high resolution we enjoy. Acuity drops rapidly as images fall outside this region [20,21], and even within the fovea cone density [22] and visual function [23] are not uniform, and attention exerts its influence [24]. To perceive the fine spatial structure of the world, we therefore need to center gaze on the area of interest by making saccadic eye movements (Box 1).

Saccades, of all sizes, are crucial for visual perception: they are as essential for vision, as is the focusing of the image onto the retina. However, they also present serious challenges to purely spatial models of vision because each saccade causes abrupt changes to the retinal images, and to their centrally projected signals. Not only do these frequent movements shift the image around – like a video filmed by a careening drunk – but they also change the cortical distortion as the center of cortical magnification travels across different parts of the visual scene. The successive snapshot of each new fixation would be uninterpretable without taking eye position into account, and high-level spatial representations require temporal integration across saccades. How the visual system achieves these goals has been subject to intense debate over the past few decades, as well-reviewed in many recent publications [25,26].

In this essay we concentrate not so much on the problems generated by eye-movements but on their benefits and how they could contribute to schemes of **temporal coding** and **spatiotemporal coding**. It is well known that the spatial acuity of human vision can vastly exceed that predicted by the retinal sampling density, even in the fovea, a phenomenon known as hyperacuity. For example, Vernier acuity (the smallest perceivable offset between two lines) can be as small as a few arcseconds, an order of magnitude smaller than the spacing of the photoreceptors [27]. Although it is commonly assumed that this level of resolution may be achieved by spatial summation mechanisms in the visual cortex, simple calculations under the actual conditions of human vision show that pure spatial integration could never lead to the actual observed resolution (Box 2). Thus, we are compelled to consider other aspects of the image, such as its temporal structure.

It is remarkable that the visual system can establish clear representations of fine spatial patterns at all, given how much the eyes actually move during the acquisition of visual information [6–8,28]. As described in Box 1, eye movements occur incessantly even when trying hard to maintain fixation on an object. In the fixational pauses, the eyes wander erratically around with a motion known as **ocular drift**, that is occasionally interrupted by miniature replicas of saccades, termed **microsaccades** [6–8] (Box 1). Although the amplitudes of the ocular drift fluctuations are close to the **eye-tracking resolution** limits of most popular devices, they are large enough to displace the stimulus over tens of foveal receptors, producing motion signals that would be immediately perceived if caused by the motion of objects in the scene, rather than by eye movements. Because neurons in the retina, thalamus, and visual cortices often integrate signals over temporal windows of 100–150 ms and more [12,13,29,30], fundamental questions

### Glossary

**Camera model of the eye:** a model in which the eye operates like a camera, taking discrete spatial snapshots of the scene, frame after frame.

**Eye-tracking resolution:** fixational eye movements reach fluctuation amplitudes that are beyond the reach of many eye-tracking devices. Analyses of eye movements should take the noise level and sensitivity of the measuring device into account in determining the lower bounds in the estimated kinematic variables.

**Fixational eye movements:** small eye movements during fixational pauses. They are traditionally subdivided into microsaccades, ocular drift, and tremor. However, the distinction between drift and tremor is challenging and is not attempted in this article.

**Fixational pause:** the period in between saccades, in which the stimulus moves relatively little on the retina. Often termed fixation for brevity.

**Fovea:** we use this term here to refer to the foveola, the small (~0.2 mm in diameter, approximately 1° in visual angle) retinal region at the center of gaze that is free from blood vessels and rod photoreceptors, and where cones are most densely packed.

**Luminance flow:** the continually changing pattern of light impinging onto the retina even during viewing of a stationary scene.

**Microsaccade:** a term that has been used to describe both the small saccades that, during normal viewing, maintain the stimulus of interest within the fovea, and the involuntary small saccades that occur in the laboratory when observers are instructed to maintain a steady gaze on a marker. Microsaccades properties are continuous with those of saccades and do not form a distinct group. Furthermore, recent evidence indicates that microsaccades act as small saccades, initiating a new fixational pause.

**Minute of arc (arcmin, minarc, or '):** a measurement unit of angle, corresponding to 1/60th of 1°. It is usually indicated by the symbol '.

**Ocular drift:** the incessant wandering of the eye during fixational

emerge about why the world does not appear blurred and how the visual system can reliably represent fine spatial detail [31–34].

How then is fine spatial vision possible? An intriguing hypothesis, raised several times over the course of almost a century [35–43], is that, instead of being detrimental, eye movements may actually be beneficial for encoding space, particularly at small scales. This happens because spatial information is not lost in the visual signals resulting from eye movements, but is instead converted into modulations that may be extracted via temporal codes.

Although this concept may at first appear counter-intuitive, one clear example of how temporal information can aid spatial analysis is motion perception (Box 3). Objects of interest are often in motion, presenting a problem for purely spatial mechanisms of neural encoding because the windows of neuronal integration are long enough for even moderate speeds of motion to smear images beyond recognition [30]. However, this does not happen: images in motion do not appear to be particularly smeared, provided that they are displayed for a sufficiently long period of time [32]. Clearly the visual system is specialized to analyze moving objects, taking their movements into account while extracting information about them [42,44] (more details in Box 3).

Motion perception is often considered to be a specialized visual function that relies on dedicated neural machinery that is separate from that normally used to process stationary spatial scenes. Although objects may be stationary in space, eye movements keep their projections in continuous motion on the retina. We argue here that motion processing is not a special case for vision, but the norm. Because there are no stationary retinal signals during natural vision, motion processing is the fundamental, basic operating mode of human vision. Thus, the visual system must always process space via temporal signals, especially those resulting from eye movements.

### Eye Movements, Like Object Motion, Link Space and Time

A well-established finding, preserved across species and types of neurons, is that retinal, thalamic, and early visual cortical neurons respond much more strongly to changing than stationary stimuli [12,13,45–47]. In the laboratory, these neurons are commonly activated by temporally modulating stimuli on the display (either by flashing or moving them), but under natural viewing conditions the most common cause of temporal modulation on the retina is our own behavior: moving our eyes. Eye movements continually transform stationary spatial scenes into a spatiotemporal **luminance flow** on the retina. When in the appropriate frequency bands, these spatiotemporal patterns can potentially strongly activate neurons along the visual system.

A helpful way to conceptualize and analyze the space-time reformatting resulting from eye movements is by means of the spectral distribution of the luminance flow, a representation of the power of the retinal stimulus over **spatial frequencies** and **temporal frequencies** (Figure 1A). When a static scene is observed with immobile eyes – a situation that never actually occurs under natural conditions – the input to the retina is a static image. Its power is confined to 0 Hz (green line in Figure 1A). Eye movements transform this static scene into a spatiotemporal flow, an operation that, in the frequency domain, is equivalent to redistributing the 0 Hz power across nonzero temporal frequencies (blue surface in Figure 1A). The exact way in which this redistribution occurs depends on the specific characteristics of the eye movements: because of their very different properties, saccades and drifts create signals with different spatiotemporal statistics on the retina.

pauses. Its power spectrum declines with the square of temporal frequency, often exhibiting a mode at around the gamma (~30–80 Hz) frequency band. This latter component is occasionally termed 'tremor'.

**Photoreceptor cells:** the neurons in the retina that convert light into electrochemical signals.

**Power spectrum:** a representation of how the power of a signal is distributed in the frequency domain.

**Retinal ganglion cells:** the neurons in the output stage of the retina which relay spike-based information to brainstem, midbrain, and thalamic areas.

**Retinal stabilization:** a laboratory procedure that aims to eliminate the physiological motion of the retinal image.

**Saccade:** the most rapid eye movement normally used to bring visual regions of interest to the foveola. Saccades typically occur 2–3 times per second.

**Spatial coding:** a coding scheme in which the information is carried by the spatial location of the receptor and the intensity of its activation.

**Spatial frequency:** the number of times a sinusoidal pattern (a grating) repeats itself within 1°.

**Spatiotemporal coding:** a coding scheme in which the information is carried by the relationships between the spatial locations of the receptors and the timing of their activations.

**Spatiotemporal receptive field:** the region of space-time that can modify the response of a neural unit.

**Temporal coding:** a coding scheme in which the information is carried by the timing of receptor activation.

**Temporal frequency:** the number of times a sinusoidal modulation repeats itself within 1 s.

**Whitening:** an operation that equalizes the power of a signal across all its frequencies (practically, within a given range). This process also removes any internal correlations in the signal.

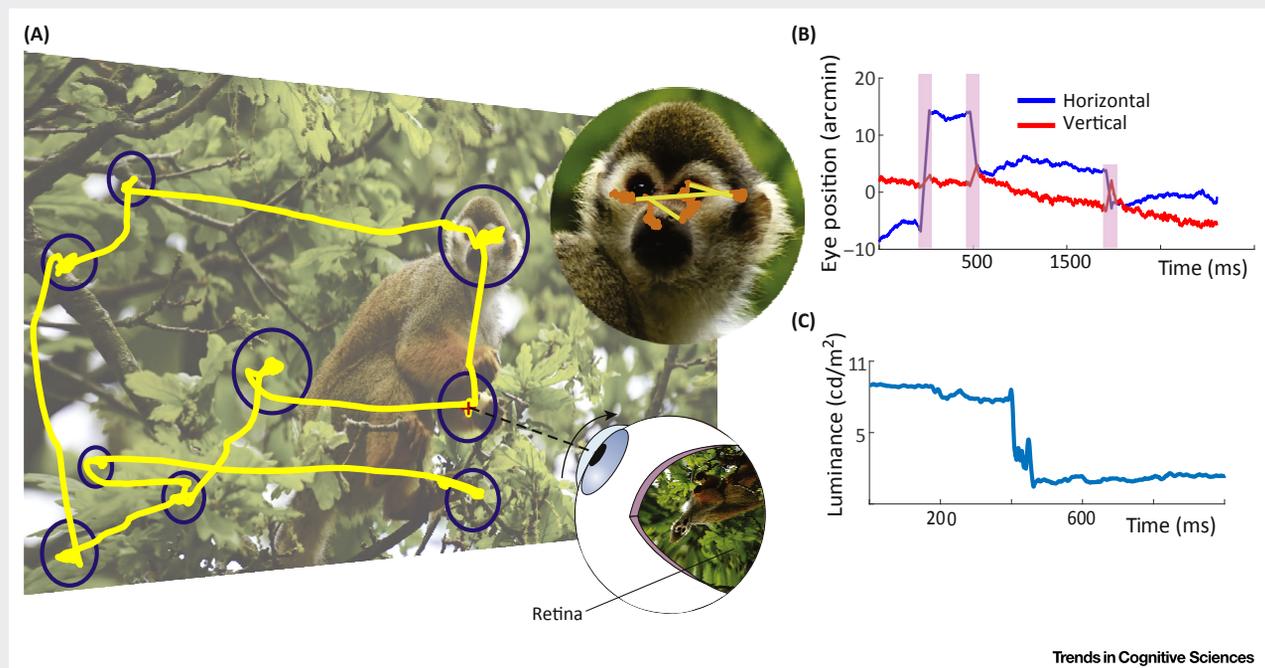
## Box 1. Exploring via Eye Movements

The human retina collects visual information from a large portion of space, a region that covers more than  $180^\circ$  along the horizontal meridian. To effectively monitor such a large visual field, visual acuity and other functions are not uniform across the retina, but progressively deteriorate with increasing distance from the fovea [20,21,90–92], the region of the retina where cones are most densely packed. This tiny area, approximately the size of the full moon, occupies less than 0.01% of the visual field. Thus, to efficiently examine a visual scene, humans must move their eyes.

Figure 1 shows a typical pattern of eye movements performed by a human observer examining a stationary scene. The primary way that the fovea is reoriented toward objects of interest is via rapid gaze shifts, known as saccades, that normally occur 2–3 times every second. Depending on the task, saccades come in a broad range of amplitudes, ranging from a few **minutes of arc** to many degrees. Small saccades, often termed microsaccades, frequently occur during examination of fine spatial patterns, precisely centering the stimulus to optimize fine spatial vision [23,52].

In the intervals in between saccades and microsaccades, the eyes move incessantly with seemingly erratic trajectories. This motion is often considered as the superposition of two separate processes: a slower wandering, often referred to as ocular drift [93,94], and a faster jittery oscillation known as tremor [95–97]. In this article we do not attempt to subdivide the intersaccadic motion of the eye, which we refer to as ‘ocular drift’ or simply ‘drift’. Ocular drift moves the eye in ways that resemble Brownian motion, frequently changing direction and maintaining the image on the retina in motion at speeds that would be immediately noticeable if resulting from the motion of objects in the scene rather than from eye movements.

When the head of the observer is immobilized, a standard condition for measuring very small eye movements, the average speed of the stimulus on the retina is approximately  $1^\circ/s$ . The mean instantaneous speed increases ( $\sim 1.5^\circ/s$ ) when the head is free to move normally, but this increment is only a fraction of what one would expect, considering that the eyes now drift more than threefold faster relative to when the head is immobilized. This happens because most of the increase in fixational eye movements acts to counterbalance fixational head movements [50,51,98], maintaining retinal image motion within levels similar to those experienced with the head constrained.



**Figure 1. Normal Eye Movements.** (A) An oculomotor trace (yellow) superimposed on the observed scene. Each fixational pause is represented by a circle with a radius proportional to its duration. The zoomed-in panel (top right) shows fixational eye movements. Both microsaccades (yellow segments) and drifts (orange) are visible. (B) Horizontal and vertical eye displacements in a portion of the trace. The shaded red regions indicate microsaccades. (C) Luminance modulations experienced by one retinal receptor as the eye changes fixation via a saccade.

## Effect of Eye Drift on Visual Input Signals

Let us first examine the spectral redistribution (the change in the input **power spectrum**) caused by ocular drift. Drift-induced retinal modulations depend on the spatial frequency of the stimulus. This happens because, as the eye moves, the luminance signals impinging onto the

## Box 2. Boundaries for the Applicability of the Camera Model to Vision

A strong argument against purely spatial mechanisms of visual encoding comes from hyperacuity, the ability to detect relative offsets between lines or dots an order of magnitude smaller than the spatial granularity of the eye ( $\sim 3'$  compared to  $20'$ ). A spatial model could account for such hyperacuity only by intensity-coding (subpixel interpolation). This could be done by optical or neural smearing, spreading visual detail across more than a single photoreceptor, allowing the intensities of retinal outputs to be interpolated to achieve super-resolution. Although there are enough cortical neurons for the required interpolation [31,99], the problem with any intensity model is that the build-up of an intensity code to allow such accurate interpolation takes time, and the eye is not steady during that time.

Intensity coding of a spatial offset (e.g., a Vernier stimulus) is based on the difference in the number of spikes emitted by two populations of retinal ganglion cells. With finite firing rates, the difference in population spike-count ( $dS$ ) induced by a spatial offset ( $dx$ , Figure 1A) increases monotonically with the duration over which spikes are counted ( $T$ ). At first approximation,  $dS$  depends on  $dx$  and the maximal firing rate ( $R$ ), but not on the population size (Appendix 3 in [40]):

$$dS = RTdp = 3RTdx \quad [I]$$

where  $dp$  is the spatial offset in units of individual photoreceptors at the center of the fovea (three receptors per arcminute) and  $dx$  is in arcminutes.

The minimally discriminable difference is  $dS = 1$  spike, the absolute lower bound for any intensity-based discrimination. Figure 1B demonstrates the codependency of this bound on  $T$  and  $dx$  (red curve) for  $R = 50$  spikes/s. The blue curve describes the mean expected diffusion distance of the gaze ( $D$ ) due to ocular drift as a function of count duration ( $T$ ), approximating ocular drift to a random walk process:

$$D = (VT)^{1/2} \quad [II]$$

where  $V$  is the speed of a single random-walk step, estimated here to be  $0.16'$ /ms.

For reliable intensity-based coding, gaze should drift less than  $dx$  during counting. Thus, the operating range is where  $dS > 1$  and  $dx > D$ . Hence, with  $R = 50$  spikes/s, a firing difference of 1 spike can be generated only for spatial offsets  $> 1'$ , offsets at least an order of magnitude larger than Vernier hyperacuity ( $\sim 0.05'$ ). To illustrate the implausibility of intensity-based coding of hyperacuity note that, to obtain a 1-spike difference for a Vernier stimulus (Figure 1A, black arrowheads) with such retinal motion, the retinal maximal rate should be  $R > 400\,000$  spikes/s.

Thus, although this estimate varies with drift characteristics, pure intensity coding does not seem to be able to account for Vernier acuity and probably not even for Snellen acuity. That mammalian visual systems do not use pure spatial coding is also supported by the finding that hyperacuity is substantially poorer than what is predicted from pure spatial processing, when assuming stationary eyes [100]. These considerations point at temporal coding as the most feasible candidate for high-resolution retinal coding and hyperacuity.

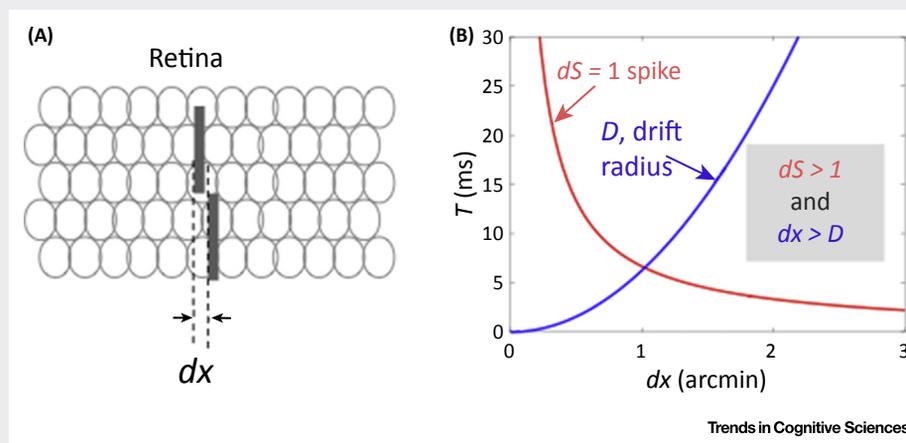


Figure 1. Boundaries for Spatial Coding of Vernier Offsets.

**Box 3. The Problem of Perceiving Moving Images without Blur**

Any motion-detection system must sample over both space and time. The simplest motion detector, often termed a Reichardt detector, samples at least two points in space, with samples being delayed over time [101]. More generally, motion selectivity implies the presence of **spatiotemporal receptive fields** orientated in space-time, as illustrated in Figure 1. This concept of spatiotemporal filtering and spatiotemporal receptive fields forms the basis of many standard models of motion perception [42,102–105].

The slant of the receptive field clearly means that it will be selective to velocity, responding well only to trajectories oriented near its long axis. However, this selectivity for motion makes the receptive field ideal to analyze the spatial form of moving objects. Because the field is aligned to the motion trajectory, it essentially annuls the motion, as if it were tracking it. The analysis is now not only a spatial analysis, but a spatiotemporal analysis, orthogonal to the long-axis of the orientation of the field. It will integrate signals within the neural unit as they traverse the field, without the blur that may be expected from a receptor array without temporal tuning.

If motion is not smooth, but stroboscopic (such as the cinema or television), it will be perceived as smooth. The system will interpolate between the motion samples. Clear evidence for spatiotemporal interpolation has been provided. If moving sampled images are perturbed only in time and not in space, by introducing a temporal offset in two Vernier line segments, the system perceives the temporal offset as a spatial offset. Moreover, it does so with very similar acuity to real spatial offset. Put another way, a spatiotemporal receptive field which traverses time and space will respond to changes in either dimension: that is to say, it allows motion to effectively convert time to space.

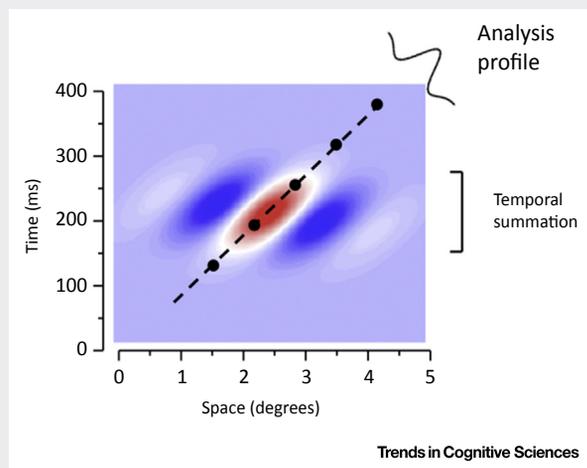
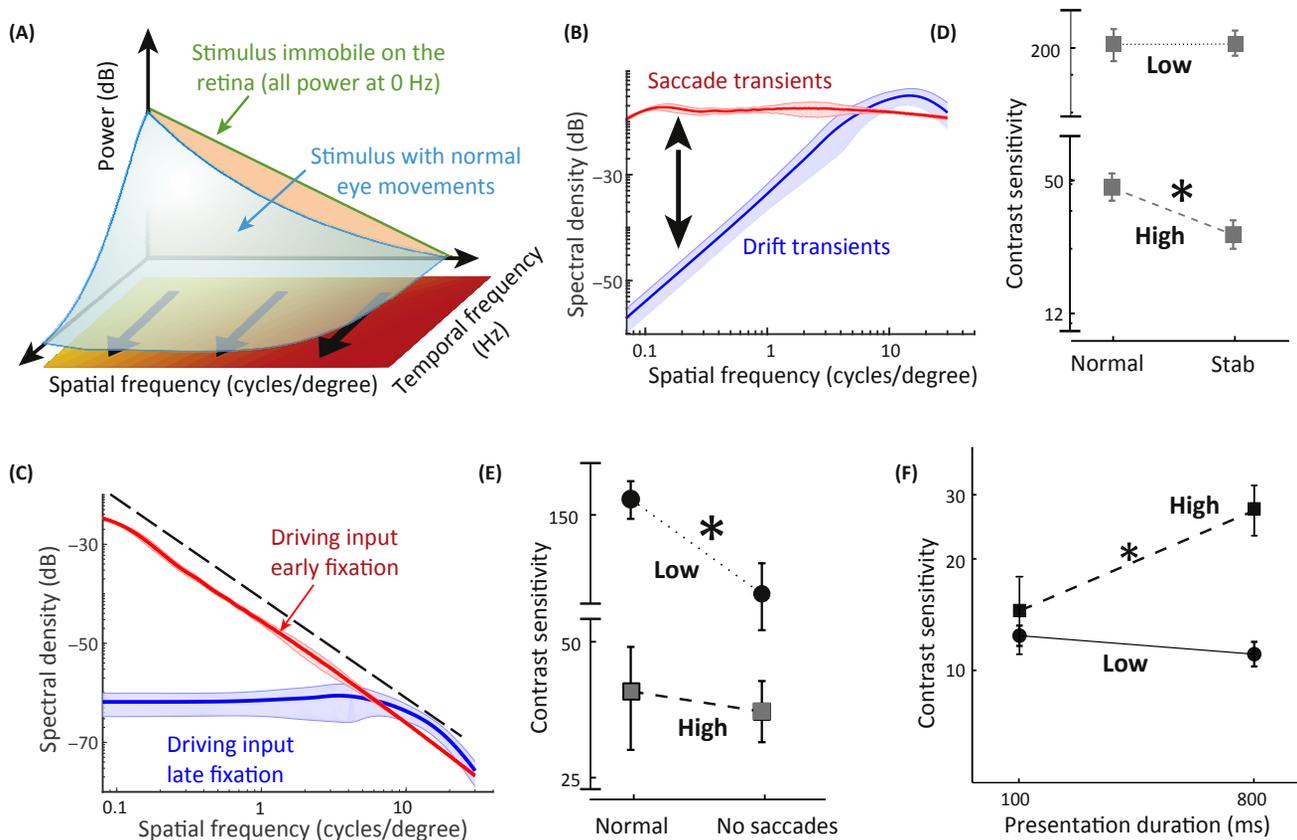


Figure 1. Spatiotemporal Sensitivity Profile of a Unit Selective to Rightward Motion. Red, positive response; blue, negative response.

retina tend to fluctuate rapidly with stimuli at high spatial frequency – stimuli that contain sharp edges and texture – but will remain more constant with smooth, low spatial frequency stimuli.

This intuition is quantitatively captured by the blue curve in Figure 1B, which shows the proportion of spatial power in the otherwise static image (the 0 Hz power) that drifts shift to non-zero temporal frequencies. For simplicity of visualization, Figure 1B shows a section of the input power at 10 Hz (averaged across all spatial directions), but sections at different nonzero temporal frequencies will be similar. The amount of power that shifts to nonzero temporal frequencies increases proportionally with the square of the spatial frequency, up to a limit that varies with the considered temporal frequency (~15 cycles/degree for 10 Hz). Power tends to grow less rapidly at higher spatial frequencies, but when summing up all temporal sections within the range of human sensitivity, an enhancement can be observed up to 30 cycles/degree, close to the spatial resolution of the photoreceptor array [37].



Trends in Cognitive Sciences

**Figure 1. Space-Time Consequences of Eye Movements.** (A) Eye movements transform spatial patterns of luminance into temporal modulations impinging on the retina. In the frequency domain, this transformation redistributes the spatial power of the stimulus from 0 Hz (green line) across nonzero temporal frequencies (blue surface) in a way that depends on the type of eye movements. (B) Spatiotemporal power redistributions resulting from saccades (red curve) and fixational drifts (blue). Each curve represents the average fraction of stimulus power that eye movements make available at 10 Hz. (C) Spectral density of the retinal input during viewing of natural scenes. Data represent average distributions at 10 Hz. The power distributions made available by saccades and drift drive cell responses at different times during the course of post-saccadic fixation. (D,E) Drift and saccade transients contribute to different ranges of visual sensitivity. Elimination of drift and saccade transients (D) impairs contrast sensitivity at 10 cycles/degree (high), but has little effect at 1 cycle/degree (low). The opposite effect occurs with elimination of saccade transients (E). (F) Timecourse of visual sensitivity during natural post-saccadic fixation. Following a saccade, contrast sensitivity continues to improve at 10 cycles/degree but not at 1 cycle/degree; \* $P < 0.03$ . Data adapted from [58].

The space-time reformatting caused by ocular drift combines with the spectral density of natural images in an interesting way [48]. The spectral power in natural scenes declines approximately with the square of the spatial frequency [49], resulting in less power at high spatial frequencies, the opposite to the amplification caused by ocular drift. Thus, the motion of the eye enhances the frequency components that have lower power in natural scenes. These two effects counterbalance each other, such that fixational modulations at different spatial frequencies contain approximately equal power up to the range at which the amplification by fixational eye movements begins to be attenuated (Figure 1C).

This equalization – known as spectral **whitening** – reveals a form of matching between normal drift and the natural world statistics. Whitening would happen for any Brownian-like eye-drift pattern, but there is a relationship between the speed of the drift (i.e., its effective diffusion constant) and the spatial frequency up to which whitening occurs. In humans, whitening occurs

only up to the spatial frequencies that can be sampled by the photoreceptors, indicating that drift motion is well matched to the characteristics of the retina.

In sum, ocular drift causes a very specific input reformatting during normal fixation, transforming natural scenes with a spectral density that is heavily biased to low spatial frequencies (the  $1/k^2$  line in Figure 1C) into luminance fluctuations with equalized spatial power at nonzero temporal frequencies. This is the dominant input signal during the late phase of inter-saccadic fixation, when neurons are no longer affected by the consequences of the preceding saccade.

Importantly, spectral whitening of the visual flow is not merely a laboratory phenomenon that only occurs when the head is restrained – a common condition in experiments in which small eye movements are recorded. When the head is free to move normally, fixational head instability also occurs, but drifts partly compensate for this motion [6,50]. As a consequence, the residual retinal image motion delivered by the interaction between fixational head and eye movements maintains spectral distributions almost identical to those measured with the head constrained [50,51].

#### Effect of Saccades and Microsaccades on Visual Input Signals

Under natural conditions, ocular drift does not occur in isolation, but alternates with rapid gaze-shifts of various magnitudes, from microsaccades (within-fovea shifts) to saccades (Box 1). These movements, both large and small, position objects of interest on the small high-acuity region of the retina known as the fovea [23,52,53]. However, in doing so they also produce sharp temporal transients to the retina, which likely drive neuronal responses in the early phase of fixation, immediately following each saccade.

As one may expect, the power redistribution caused by these rapid eye movements differs considerably from that caused by ocular drift. Unlike fixational drift modulations, these abrupt changes redistribute temporal power in a similar way across a broad range of spatial frequencies (red curve in Figure 1B), preserving the spectral distributions of the external scene. This implies that, during viewing of natural scenes, the power of the visual input to the retina will decline with the square of spatial frequency, like the spectrum of natural images, at all relevant non-zero temporal frequencies (see distributions at 10 Hz in Figure 1C). Because of this effect, saccades transiently generate more temporally modulated power than drift at low spatial frequencies, and comparable power  $\sim 10$  cycles/degree.

In sum, during natural viewing, the normal alternation between saccades and fixational drifts sequentially exposes neurons to modulations with different types of spatial information. At fixation onset, neurons respond to an input signal dominated by low spatial frequencies: later during fixation, the ocular drift enhances power at high spatial frequencies, and the same neurons are now driven by a visual flow with equal power across spatial frequencies (Figure 1C).

#### Perceptual Consequences of Oculomotor-Induced Temporal Modulations

The arguments above clearly show that the standard assumption that the input to the retina is a stationary image is a gross simplification. In reality, neurons are exposed to a complex spatiotemporal flow that cyclically changes statistics during normal eye movements. However, do these input modulations have real and important consequences for perception?

Consider first the visual signals originating from ocular drift. These modulations are predicted to enhance retinal responses to high spatial frequencies. This hypothesis can be tested experimentally by a technique, known as **retinal stabilization**, which attempts to eliminate – and in

practice drastically reduces – retinal image motion, by counter-moving the stimulus in real time against the eye movement [5,54,55]. Consistent with predictions, recent evidence shows that eliminating drift movements selectively impairs sensitivity at high spatial frequencies [56–58].

Figure 1D compares contrast sensitivity measured for an observer under normal viewing conditions, and with drift movements stabilized. As expected from the space-time reformatting shown in Figure 1D, reduction of drift movements strongly decreases sensitivity at 10 cycles/degree, but has virtually no impact at 1 cycle/degree. Interestingly, these findings conflict with the widespread belief that fixational drift is primarily helpful to prevent image fading at low spatial frequencies [15,59,60]. On the contrary, human vision takes advantage of drift modulations to enhance detailed spatial information, providing strong support to longstanding dynamic theories of visual acuity [36].

The power redistributions in Figure 1C suggest that saccades boost low spatial frequencies relative to fixational drift. This prediction is confirmed by experiments in which the normal visual transient caused by a saccade is eliminated. The data in Figure 1E summarize results from an experiment in which subjects performed a large saccade under two conditions: in the first, the stimulus (a grating at either 1 or 10 cycles/degree) appeared as soon as the saccade was detected, to expose the fovea to the normal transients elicited by the saccade; in the other the stimulus was slowly faded in after the end of the saccade, to completely eliminate the saccade-generated transient. Elimination of the saccade transient strongly reduces sensitivity at 1 cycle/degree, but has virtually no effect at 10 cycles/degree. Thus, consistent with the power redistributions of Figure 1B, at low spatial frequencies, modulations from saccades and drifts cannot be traded because the latter are not beneficial in this range, regardless of their duration.

### A Coarse-to-Fine Strategy of Visual Analysis

These considerations carry important implications regarding the formation of spatial representations, and their dynamics. Because retinal neurons are cyclically exposed to temporal transients with different spatial content, one may expect the perceptual process responsible for establishing spatial representations to be tuned to the oculomotor cycle. To optimally accrue spatial information from the oculomotor-shaped retinal input flow, an observer should rely heavily on saccade transients to extract low spatial frequencies, and integrate this information throughout the course of fixation with spatial frequency information. In other words, low spatial frequencies should be processed before high spatial frequencies.

The visual system appears to follow these dynamics. As shown in Figure 1F, sensitivity to low spatial frequency quickly reaches its plateau shortly after the end of a saccade, and changes little during the course of fixation; by contrast, sensitivity to high spatial frequencies can increase more than twofold over a 1 s interval [58]. This leads to a sequential coarse-to-fine analysis during each post-saccadic fixation, first the coarser structure given by low spatial frequencies, followed by a fine-scale analysis of higher spatial frequencies. This strategy may enable tuning of visual processing via control of eye movements, for example by performing shorter fixational pauses in low spatial frequency tasks, and could help the system integrate successive fixations, locking the low-frequency information that can be resolved outside central vision.

That mechanisms tuned to high spatial frequencies have longer processing times than those tuned to low has long been known. It goes back to early ideas of ‘sustained and transient’ channels [30,61]. This different timing also maps into the anatomically based distinction of magnocellular and parvocellular streams (M- and P-streams), with the M-stream preferring low spatial and high temporal frequencies, and the P-stream vice versa [47]. However, why should

neurons sensitive to separate spatial frequency ranges also differ in their temporal characteristics?

Our observations suggest an answer to this question. In a system designed to encode space through time, analysis of low but not high spatial frequencies tends to be more reliable immediately following a saccade than later during fixation. Distinct temporal strategies are, therefore, necessary for efficient acquisition of spatial information in different frequency ranges, and the spatiotemporal characteristics of magnocellular and parvocellular neurons are well suited to carry out these functions. In keeping with this proposal, it has been shown in macaque primary visual cortex (V1) that the neurons that are activated by drifts have smaller receptive fields, a longer response latency, and prefer slower stimulus motion compared to neurons transiently activated by microsaccades and saccades, that have larger receptive fields and faster responses [46].

### Possible Strategies for Space-Time Encoding

The previous considerations highlight the importance of eye movements in transforming a static spatial scene into a spatiotemporal flow on the retina, and some of the perceptual consequences. What, however, are the neural mechanisms that take advantage of this transformation? Neurophysiological investigations have only recently started to examine the beneficial consequences of eye movements [46,62–73], but multiple theoretical possibilities emerge. Given how closely the temporal power in the retinal flow predicts visual responses, and the close relationship between power and temporal correlation (the power spectrum is the Fourier transform of the autocorrelation function), an obvious candidate is the structure of correlated neural activity in the early stages of the visual system, particularly zero-lag correlations, because synchronous neuronal firing is already known to crucially enhance the efficacy of neural propagation [74,75].

The spectral distributions in Figure 1C directly predict that (i) the saccade-drift alternation would first elicit broad pools of simultaneously active neurons immediately after a saccade, and (ii) that these pools progressively shrink during fixation to eventually yield a pattern of uncorrelated activity (a direct consequence of the ‘whitened’ flow resulting from eye drift) during viewing of natural scenes [76]. Because the synchronous neuronal responses would signal the contrast changes induced by eye movements, they would first encode the general low spatial frequency structure of the visual scene immediately after a saccade; and they would then convey the pattern of edges (local changes in contrast) later during fixation [77]. These same mechanisms could be responsible for representing the gist of the scene immediately following the first few saccades.

Equalizing the power of a signal across spatial frequencies is equivalent to discarding spatial correlations, thereby reducing the intrinsic redundancy of natural scenes, which many theories of vision regard as essential for efficient encoding [78–80]. What is interesting, however, is that the normal drift pattern of the eyes ensures that this decorrelation occurs in the input signals themselves, before any neural processing takes place. Indeed, physiological recordings *in vitro* support the proposal that fixational instability reduces the extent of correlated activity relative to abrupt onset of the stimulus [68]. This operation removes the average pairwise correlations present in natural scenes, while leaving higher-order correlations, such as edges. It discards components of the image that are predictable from the general structure of natural scenes, thus emphasizing the features of the specific image under examination.

The use of synchronous modulations is only one of the many strategies by which the visual system can extract, encode, and decode spatial information from the incoming spatiotemporal flow. Encoding temporal strategies can take multiple forms. One basic form is the scheme of frequency coding. Because eye movements convert spatial offsets into temporal delays, two contrast changes separated in the image by a distance  $dx$  will activate a given photoreceptor (or **retinal ganglion cell**) sequentially, with a delay of  $dt$  ( $dt = dx/v$ , where  $v$  is eye velocity). Thus, spatial frequencies can be signaled via the temporal frequencies of spikes [40,41,81]. Another form of temporal encoding is the scheme of phase coding: two receptors (or ganglion cells) will be activated with a delay  $dt$  proportional to the spatial offset  $dx$  between the contrast changes they face.

These schemes allow high-resolution coding of shape, texture, and motion [40]. Importantly, in these schemes, spatial resolution would depend on the resolution of neuronal temporal processing, rather than on the spatial granularity of the receptor layout on the retina, providing a possible explanation for the mechanisms of fine spatial vision and hyperacuity [40,41]. Furthermore, as hypothesized by some of us, the visual system could take advantage of the temporal power generated by eye movements to synchronize cortical circuits (oscillators) engaged in thalamocortical phase-locked loops [40,82–84]. Ocular drift provides strong modulations in the low-temporal frequency range [40,85,86]; locking to these modulations would be beneficial, during fixational pauses, for decoding the incoming flow and extracting spatial patterns and motion information [40].

### Concluding Remarks and Future Perspectives

In this brief essay we suggest an alternative, non-conventional view of how the visual system encodes and represents space. Instead of relying exclusively on the standard spatial coding scheme in which spatial information is conveyed solely by the position of neurons within maps, we argue that spatial representations primarily rely on temporal signals resulting from self-motion, particularly eye movements. Furthermore, we argue that this strategy of converting space to time likely employs mechanisms that are also responsible for the perception of visual motion.

Multiple predictions emerge, some of which are summarized in the Outstanding Questions. Depending on the specific neural mechanisms responsible for encoding temporal signals, there may be distinct coding patterns for shape, texture, and motion. For example, fine detail of shape may be encoded primarily by inter-receptor temporal phase (representing external spatial phase), texture primarily by instantaneous intra-burst frequencies of individual receptors (representing external spatial frequencies), and motion by inter-burst temporal frequencies (representing Doppler shifts generated by the relative motion of the eye and external objects) [40].

Furthermore, although in this essay we have specifically focused on the consequences of eye movements on the retinal input, the mechanisms of spatial encoding may benefit from extraretinal information for fixational eye movements because both microsaccades [23,52,87] and ocular drift [50,51,88,89] are under control. If, on the contrary, extraretinal copies of ocular drift are not available or not used, one would expect (i) artificially generated temporal lags to be perceived as spatial offsets, and (ii) that jittered full-field scenes (unlike non-coherent motion of parts of the scene) should go unnoticed without impairing spatial vision and hyperacuity.

The more general conclusion from the considerations discussed here is that primates plan their various eye movements not only to position objects of interest on the fovea but also to generate the temporal transients that most effectively emphasize the spatial scales relevant to the task. These and other emerging hypotheses will be the focus of future investigations.

### Outstanding Questions

How is visual information acquired? (i) When does acquisition occur? Upon landing of a saccade on a new region of interest, during the fixational pause, or during both? (ii) How does acquisition occur? Via spatial coding (the 'camera model', which we argue strongly against), via temporal coding, or via spatiotemporal coding?

How is visual information processed? Addressing this question is entangled with major sub-questions: what makes the world perceived as stable in spite of sensor motion? Is processing based on open- or closed-loop environment-brain dynamics? Is central processing locked to eye movements, and if so to which components? Do spatial perception and motion perception rely on similar mechanisms?

Do primates actively control eye movements to take advantage of their temporal transients? In principle, eye movements could be controlled independently from foveation to select the scale of visual processing, emphasize task-relevant ranges of spatial details, and determine the resolution of temporal coding. It is presently unknown whether humans and other primates employ this form of active control and, if so, what are the controlled variables.

Do saccades establish a clock for visual decoding? To effectively make use of the spatial information contained in the luminance modulations resulting from eye movements, analysis of neural activity needs to be timed relative to the occurrence of saccades. For example, a spike from the same neuron carries a different informational value if it occurs during early fixation, when the input change caused by the preceding saccade still exerts its influence, or later, when temporal changes are only caused by ocular drift.

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